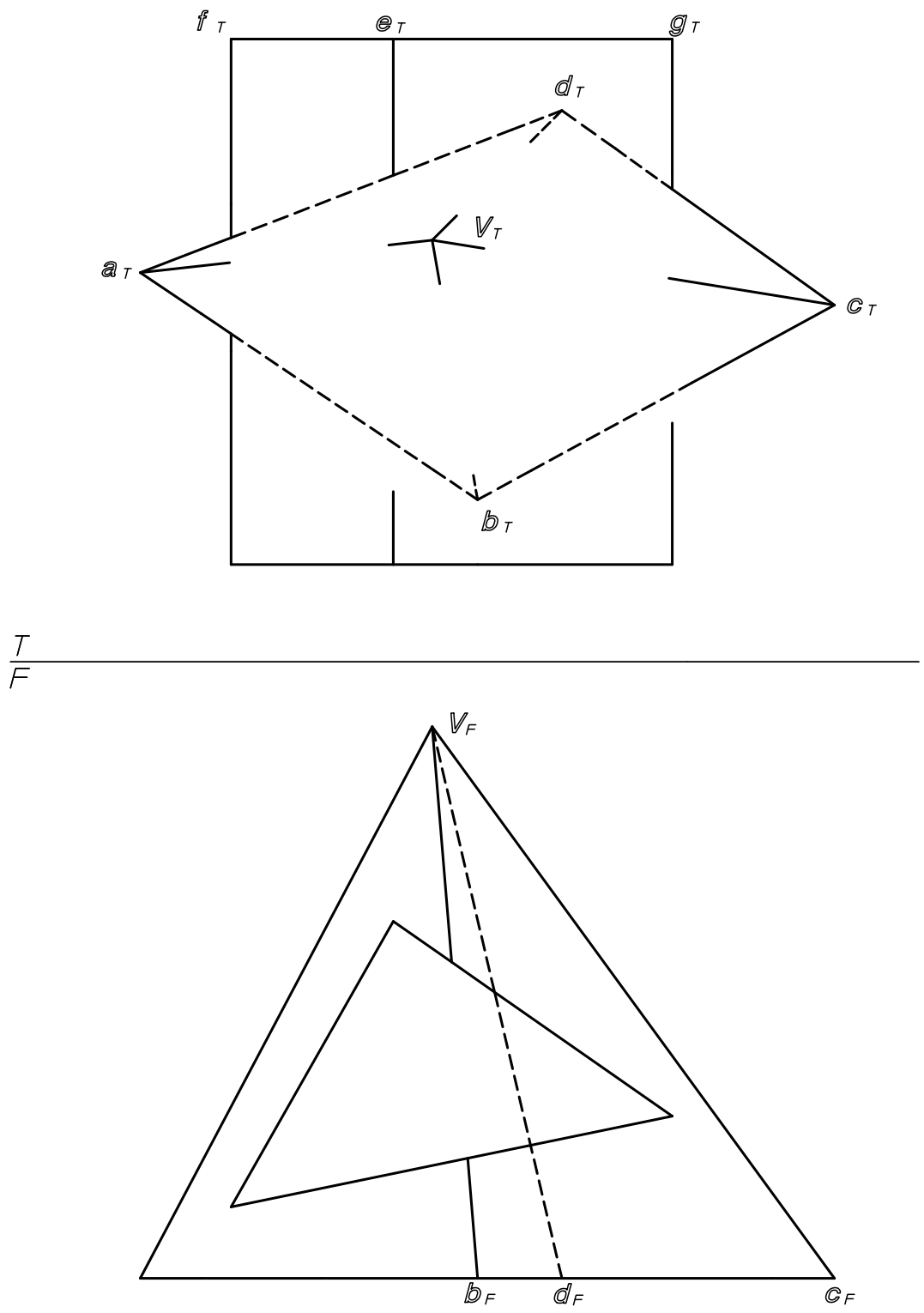
f_T
e_T
g_T
d_T
V_T
a_T
c_T
b_T
$\frac{T}{F}$
V_F
b_F
d_F
c_F